

13. Properties of Least Squares

Spring 2023

Matthew Blackwell

Gov 2002 (Harvard)

Where are we? Where are we going?

- Before: learned about CEFs and linear projections in the population.

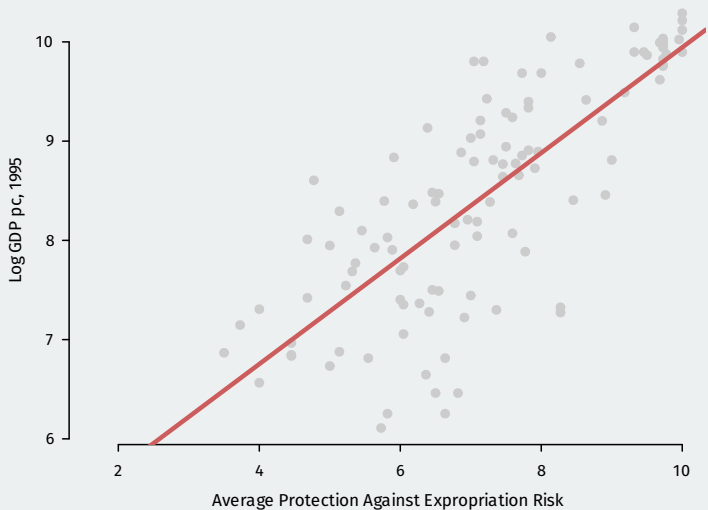
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- Last time: OLS estimator, its algebraic properties.
- Now: its statistical properties, both finite-sample and asymptotic.

Political Institutions and Economic Development



Sampling distribution of the OLS estimator

- OLS is an estimator—we plug data into and we get out estimates.

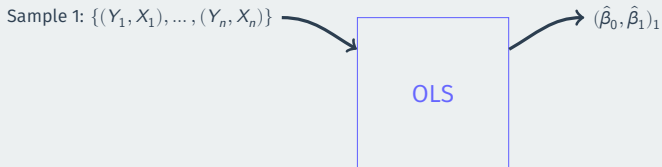
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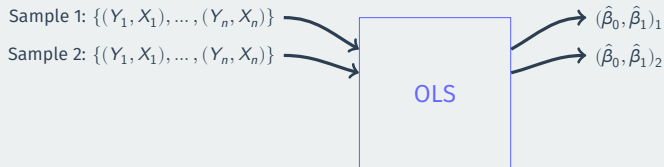
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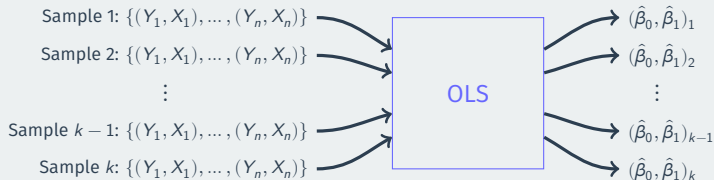
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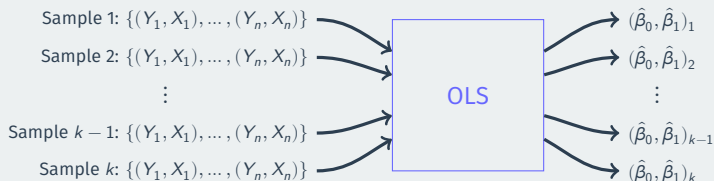
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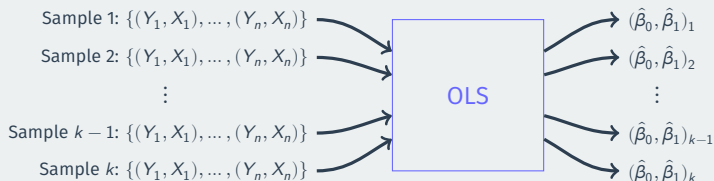
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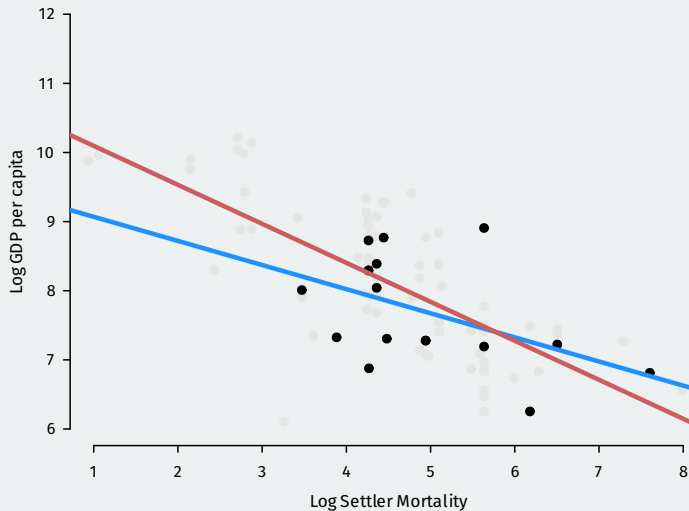
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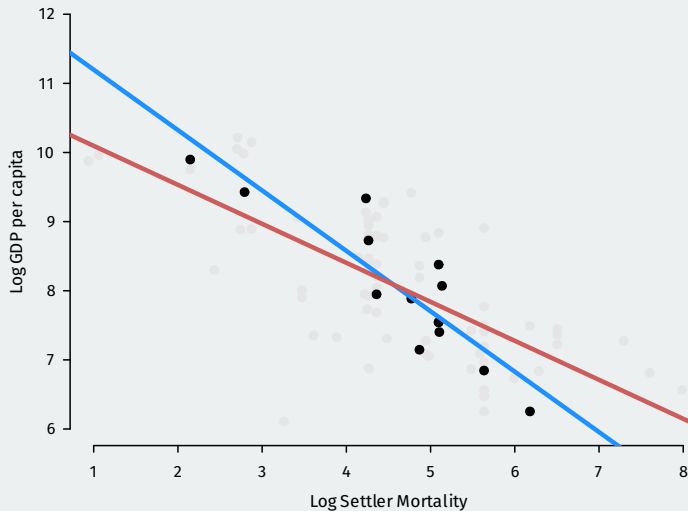
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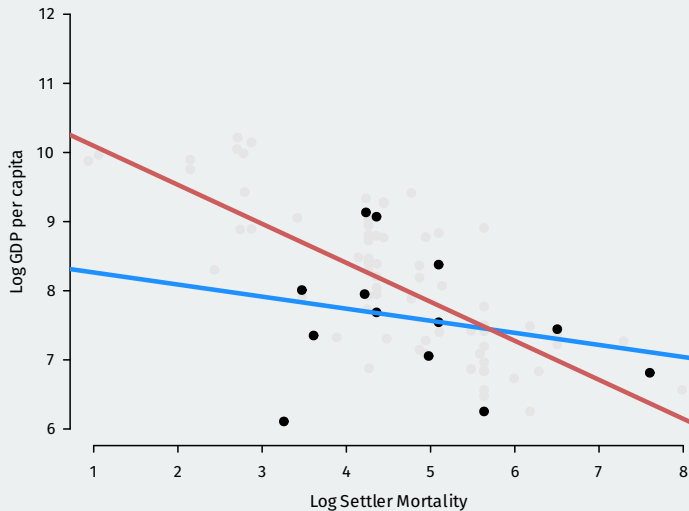
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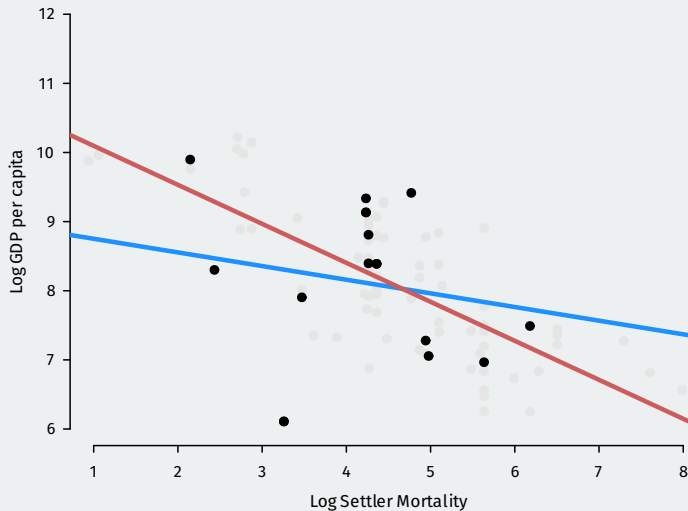
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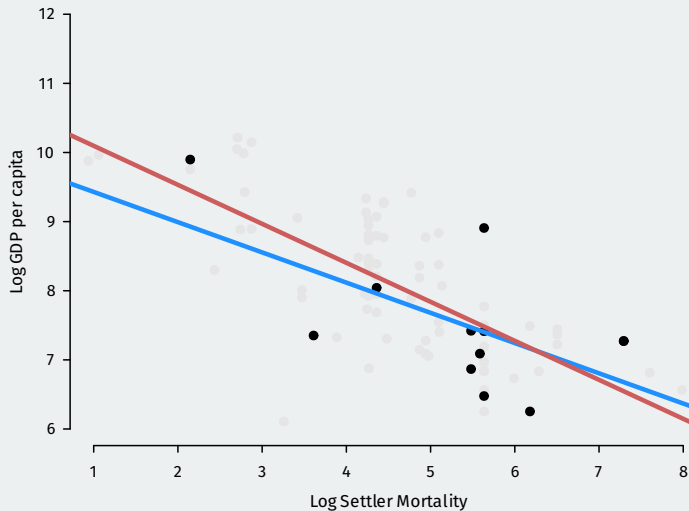
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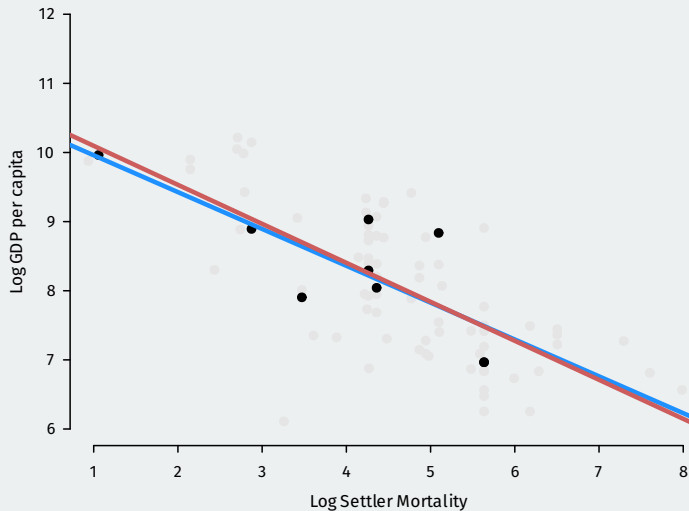
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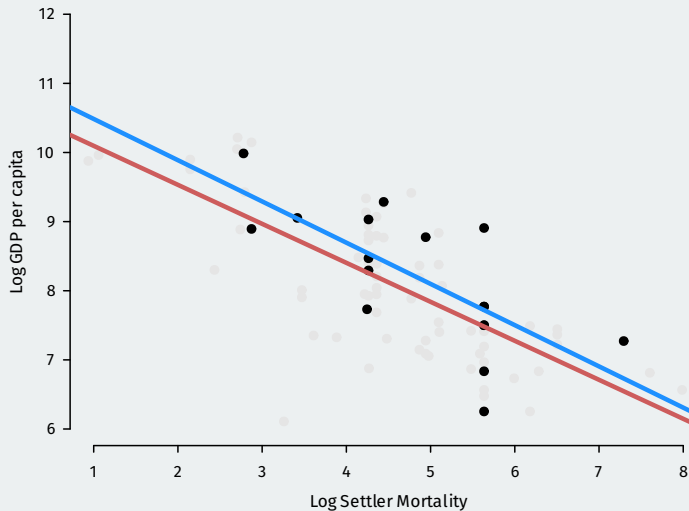
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 - **Linear regression/CEF model** for finite samples.

1/ Linear projection model and Large-sample Properties

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1. For the variables (Y, \mathbf{X}) , we assume the linear projection of Y on \mathbf{X} is defined as:

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- What properties can we derive under such weak assumptions?

A very useful decomposition

$$\hat{\boldsymbol{\beta}} = \left(\frac{1}{n} \sum_{i=1}^n \mathbf{x}_i \mathbf{x}_i' \right)^{-1} \left(\frac{1}{n} \sum_{i=1}^n \mathbf{x}_i Y_i \right) = \boldsymbol{\beta} + \underbrace{\left(\frac{1}{n} \sum_{i=1}^n \mathbf{x}_i \mathbf{x}_i' \right)^{-1} \left(\frac{1}{n} \sum_{i=1}^n \mathbf{x}_i e_i \right)}_{\text{estimation error}}$$

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- Sample means in the estimation error follow the law of large numbers:

$$\frac{1}{n} \sum_{i=1}^n \mathbf{x}_i \mathbf{x}_i' \xrightarrow{p} \mathbb{E}[\mathbf{x}_i \mathbf{x}_i'] \equiv \mathbf{Q}_{\mathbf{X}\mathbf{X}} \quad \frac{1}{n} \sum_{i=1}^n \mathbf{x}_i e_i \xrightarrow{p} \mathbb{E}[\mathbf{x}_i e_i] = \mathbf{0}$$

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- $\mathbf{Q}_{\mathbf{X}\mathbf{X}}$ is invertible by assumption, so by the continuous mapping theorem:

$$\left(\frac{1}{n} \sum_{i=1}^n \mathbf{x}_i \mathbf{x}_i' \right)^{-1} \xrightarrow{p} \mathbf{Q}_{\mathbf{X}\mathbf{X}}^{-1} \implies \hat{\beta} \xrightarrow{p} \beta + \mathbf{Q}_{\mathbf{X}\mathbf{X}}^{-1} \cdot \mathbf{0} = \beta,$$

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- Valid with no restrictions on Y : could be binary, discrete, etc.
- Not guaranteed to be unbiased (unless CEF is linear, as we'll see...)

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$$\mathbb{E} \left[\frac{1}{n} \sum_{i=1}^n g(\mathbf{X}_i) \right] = \mathbb{E}[g(\mathbf{X}_i)] \quad \text{var} \left[\frac{1}{n} \sum_{i=1}^n g(\mathbf{X}_i) \right] = \frac{\text{var}[g(\mathbf{X}_i)]}{n}$$

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- If $\mathbb{E}[g(\mathbf{X}_i)] = 0$, then we have

$$\sqrt{n} \left(\frac{1}{n} \sum_{i=1}^n g(\mathbf{X}_i) \right) = \frac{1}{\sqrt{n}} \sum_{i=1}^n g(\mathbf{X}_i) \xrightarrow{d} \mathcal{N}(0, \mathbb{E}[g(\mathbf{X}_i)g(\mathbf{X}_i)'])$$

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 - Rewrite as \sqrt{n} times an average of i.i.d. mean-zero random vectors.
- Let $\boldsymbol{\Omega} = \mathbb{E}[e_i^2 \mathbf{x}_i \mathbf{x}_i']$ and apply the CLT:

$$\left(\frac{1}{\sqrt{n}} \sum_{i=1}^n \mathbf{x}_i e_i \right) \xrightarrow{d} \mathcal{N}(0, \boldsymbol{\Omega})$$

Asymptotic normality

Theorem (Asymptotic Normality of OLS)

Under the linear projection model,

$$\sqrt{n}(\hat{\boldsymbol{\beta}} - \boldsymbol{\beta}) \xrightarrow{d} \mathcal{N}(0, \mathbf{V}_{\boldsymbol{\beta}}),$$

where,

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Theorem (Asymptotic Normality of OLS)

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- Allows us to formulate (approximate) confidence intervals, tests.

2/ OLS variance estimation

Estimating OLS variance

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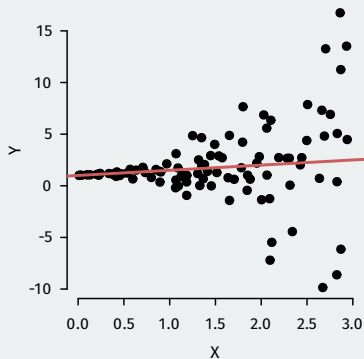
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- Square root of the diagonal of $\widehat{\mathbf{V}}_{\hat{\boldsymbol{\beta}}} = n^{-1} \widehat{\mathbf{V}}_{\boldsymbol{\beta}}$:
heteroskedasticity-consistent (HC) SEs (aka “robust SEs”)

Homoskedasticity

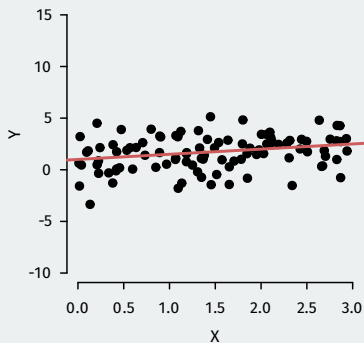
Assumption: Homoskedasticity

The variance of the error terms is constant in \mathbf{X} , $\mathbb{E}[e^2 | \mathbf{X}] = \sigma^2(\mathbf{X}) = \sigma^2$.

Heteroskedastic



Homoskedastic



Consequences of homoskedasticity

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- LLN implies $s^2 \xrightarrow{p} \sigma^2$ and so $n\widehat{\mathbf{V}}_{\hat{\boldsymbol{\beta}}}^{\text{lm}}$ is consistent for $\mathbf{V}_{\boldsymbol{\beta}}^{\text{lm}}$

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- Lots of “flavors” of HC variance estimators (HC0, HC1, HC2, etc).
 - Mostly small, ad hoc changes to improve finite-sample performance.

AJR data

```
library(sandwich)
mod <- lm(logpgp95 ~ avexpr + lat_abst + meantemp, data = ajr)
vcov(mod) ## homoskedastic  $V_{\hat{\beta}}$ 
```

```
##           (Intercept)    avexpr  lat_abst  meantemp
## (Intercept)    0.9079 -0.040952 -0.537463 -0.023246
## avexpr         -0.0410  0.004162 -0.000778  0.000605
## lat_abst       -0.5375 -0.000778  0.867588  0.016717
## meantemp       -0.0232  0.000605  0.016717  0.000705
```

```
sandwich::vcovHC(mod, type = "HC2") ## HC2
```

```
##           (Intercept)    avexpr  lat_abst  meantemp
## (Intercept)    0.9764 -0.05735 -0.29548 -0.024639
## avexpr         -0.0573  0.00538 -0.00358  0.001107
## lat_abst       -0.2955 -0.00358  0.60821  0.008792
## meantemp       -0.0246  0.00111  0.00879  0.000706
```

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- Software often uses t critical values instead of normal (we'll see why).

Inference with `lmtest::coeftest()`

```
library(lmtest)
## homoskedastic error
lmtest::coeftest(mod)

##
## t test of coefficients:
##
##           Estimate Std. Error t value Pr(>|t|)
## (Intercept)  6.9289    0.9528    7.27 1.2e-09 ***
## avexpr       0.4059    0.0645    6.29 5.1e-08 ***
## lat_abst    -0.1980    0.9314   -0.21  0.832
## meantemp    -0.0641    0.0266   -2.41  0.019 *
## ---
## Signif. codes:
## 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

```
## HC2 variance estimator
lmtest::coeftest(mod, vcov = vcovHC(mod, type = "HC2"))
```

```
##
## t test of coefficients:
##
##           Estimate Std. Error t value Pr(>|t|)
## (Intercept)  6.9289    0.9881    7.01 3.3e-09 ***
## avexpr       0.4059    0.0733    5.53 8.6e-07 ***
## lat_abst    -0.1980    0.7799   -0.25  0.801
## meantemp    -0.0641    0.0266   -2.41  0.019 *
## ---
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3/ Inference for Multiple Parameters

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$$\mathbb{V} \left(\frac{\partial \widehat{m}(x, z)}{\partial x} \right) = \mathbb{V} [\widehat{\beta}_1 + z\widehat{\beta}_3] = \mathbb{V}[\widehat{\beta}_1] + z^2\mathbb{V}[\widehat{\beta}_3] + 2z\text{cov}[\widehat{\beta}_1, \widehat{\beta}_3]$$

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- Use the estimated covariance matrix:

$$\widehat{\mathbb{V}} \left(\frac{\partial \widehat{m}(x, z)}{\partial x} \right) = \widehat{\mathbb{V}}_{\widehat{\beta}_1} + z^2\widehat{\mathbb{V}}_{\widehat{\beta}_3} + 2z\widehat{\mathbb{V}}_{\widehat{\beta}_1\widehat{\beta}_3}$$

Inference for interactions

$$m(x, z) = \beta_0 + X\beta_1 + Z\beta_2 + XZ\beta_3$$

- **Partial** or **marginal** effect of X at Z : $\frac{\partial m(x, z)}{\partial x} = \beta_1 + z\beta_3$
- Estimate it by plugging in the estimated coefficients: $\frac{\partial \widehat{m}(x, z)}{\partial x} = \widehat{\beta}_1 + z\widehat{\beta}_3$
- What if we want the variance of this effect for any value of Z ?

$$\mathbb{V} \left(\frac{\partial \widehat{m}(x, z)}{\partial x} \right) = \mathbb{V} [\widehat{\beta}_1 + z\widehat{\beta}_3] = \mathbb{V}[\widehat{\beta}_1] + z^2\mathbb{V}[\widehat{\beta}_3] + 2z\text{cov}[\widehat{\beta}_1, \widehat{\beta}_3]$$

- Use the estimated covariance matrix:

$$\widehat{\mathbb{V}} \left(\frac{\partial \widehat{m}(x, z)}{\partial x} \right) = \widehat{\mathbb{V}}_{\widehat{\beta}_1} + z^2\widehat{\mathbb{V}}_{\widehat{\beta}_3} + 2z\widehat{\mathbb{V}}_{\widehat{\beta}_1\widehat{\beta}_3}$$

- $\widehat{\mathbb{V}}_{\widehat{\beta}_1}$ is the diagonal entry of $\widehat{\mathbb{V}}_{\widehat{\beta}}$ for $\widehat{\beta}_1$

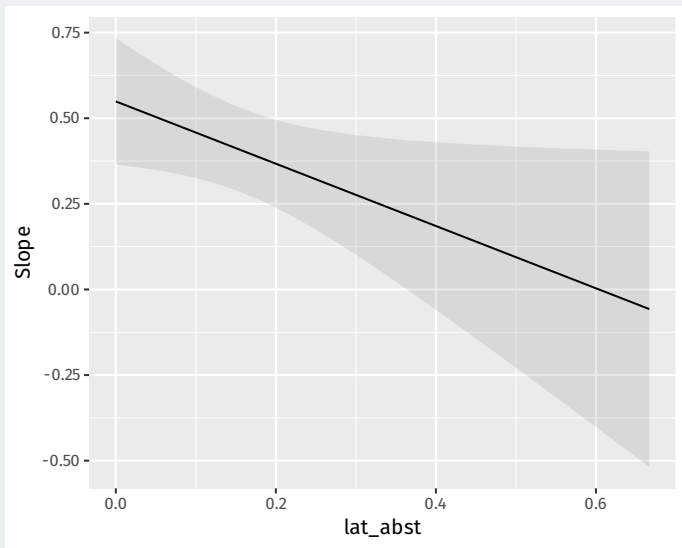
Visualizing via marginalesffects

```
int_mod <- lm(logpgp95 ~ avexpr * lat_abst + meantemp, data = ajr)
coeftest(int_mod)
```

```
##
## t test of coefficients:
##
##           Estimate Std. Error t value Pr(>|t|)
## (Intercept)    6.9864    0.9273    7.53  5e-10
## avexpr         0.5491    0.0941    5.84  3e-07
## lat_abst      5.8152    3.0791    1.89  0.0642
## meantemp      -0.1048    0.0326   -3.21  0.0022
## avexpr:lat_abst -0.9095    0.4451   -2.04  0.0458
##
## (Intercept)    ***
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## lat_abst      .
## meantemp      **
## avexpr:lat_abst *
## ---
## Signif. codes:
## 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

Visualizing marginal effects

```
library(marginaleffects)  
plot_slopes(int_mod, variables = "avexpr", condition = "lat_abst")
```



Tests of multiple coefficients

$$m(X, Z) = \beta_0 + X\beta_1 + Z\beta_2 + XZ\beta_3$$

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 - Need to normalize like the t-statistic.

Alternative test for one coefficient

- Usually t-test of $H_0 : \beta_j = b_0$ based on the t-statistic:

$$t = \frac{\hat{\beta}_j - b_0}{\widehat{\text{se}}(\hat{\beta}_j)},$$

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Rewriting hypotheses with matrices

- We can rewrite the null hypothesis as $H_0 : \mathbf{L}\boldsymbol{\beta} = \mathbf{c}$ where,

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- If this covariance matrix were identity, then these would be standard normal and $\hat{\beta}_1^2 + \hat{\beta}_3^2$ would be χ_2^2 under the null

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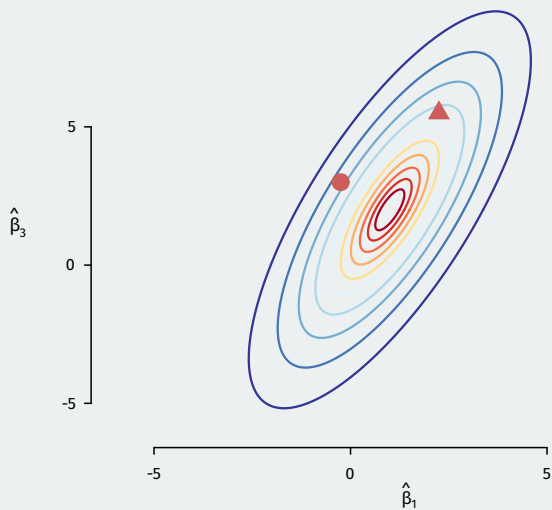
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- Squared distance of observed values from the null, weighted by the distribution of the parameters under the null

Weighting by the distribution



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 - “Usual” F-test reports test of all coef = 0 except intercept (pointless?)

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 - When applied to a single coefficient, equivalent to a t-test.
 - Use packages like `{lmtest}` or `{clubSandwich}` in R.

Wald test in `lmtest`

```
## run OLS with the restrictions imposed (avexpr removed)
restricted <- lm(logpgp95 ~ lat_abst + meantemp, data = ajr)

## pass estimated model and estimated null model to
## wald test with HC variance estimator
lmtest::waldtest(restricted, int_mod, test = "Chisq",
                 vcov = vcovHC)
```

```
## Wald test
##
## Model 1: logpgp95 ~ lat_abst + meantemp
## Model 2: logpgp95 ~ avexpr * lat_abst + meantemp
##   Res.Df Df Chisq Pr(>Chisq)
## 1      57
## 2      55  2  34.2   3.7e-08 ***
## ---
## Signif. codes:
## 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
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 - Run a regression of the first variable on the rest.
- By design, no effect of any variable on any other.

Multiple test example

```
noise <- data.frame(matrix(rnorm(2100), nrow = 100, ncol = 21))
summary(lm(noise))
```

```
##
## Coefficients:
##           Estimate Std. Error t value Pr(>|t|)
## (Intercept) -0.028039   0.113820  -0.25  0.8061
## X2          -0.150390   0.112181  -1.34  0.1839
## X3           0.079158   0.095028   0.83  0.4074
## X4          -0.071742   0.104579  -0.69  0.4947
## X5           0.172078   0.114002   1.51  0.1352
## X6           0.080852   0.108341   0.75  0.4577
## X7           0.102913   0.114156   0.90  0.3701
## X8          -0.321053   0.120673  -2.66  0.0094 **
## X9          -0.053122   0.107983  -0.49  0.6241
## X10          0.180105   0.126443   1.42  0.1583
## X11          0.166386   0.110947   1.50  0.1377
## X12          0.008011   0.103766   0.08  0.9387
## X13          0.000212   0.103785   0.00  0.9984
## X14          -0.065969   0.112214  -0.59  0.5583
## X15          -0.129654   0.111575  -1.16  0.2487
## X16          -0.054446   0.125140  -0.44  0.6647
## X17          0.004335   0.112012   0.04  0.9692
## X18          -0.080796   0.109853  -0.74  0.4642
## X19          -0.085806   0.118553  -0.72  0.4713
## X20          -0.186006   0.104560  -1.78  0.0791 .
## X21           0.002111   0.108118   0.02  0.9845
## ---
## Signif. codes:
## 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 0.999 on 79 degrees of freedom
## Multiple R-squared:  0.201, Adjusted R-squared: -0.00142
## F-statistic: 0.993 on 20 and 79 DF, p-value: 0.48
```

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 - Example: $0.05/20 = 0.0025$
 - Ensures that the family-wise error rate (probability of making at least 1 Type I error) is less than α .

4/ Linear Regression Model and Finite-sample Properties

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Assumption: Linear Regression Model

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- We continue to maintain $\{(Y_i, \mathbf{X}_i)\}$ are i.i.d.

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- Useful when linearity holds by default (discrete X in experiments, etc)

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- Upshot: OLS will have the smaller SEs than any other linear estimator.

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- With reasonable n , asymptotic normality has the same effect.