14. Panel and Clustered Data

Spring 2023

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Gov 2002 (Harvard)

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- Panel data also holds hope for removing unmeasured heterogeneity.

1/ Panel Data

Michael Ross University of California, Los Angeles

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 - · provide benefits more efficiently
 - · posses some cultural trait correlated with better health outcomes
- If have data on countries over time, can we make any progress in spite of these problems?

Ross data

```
library(tidyverse)
library(haven)
ross <- read_dta("../assets/ross-democracy.dta")
ross <- ross |>
  filter(!is.na(kidmort_unicef), !is.na(democracy), !is.na(GDPcur)) |>
  group_by(id) |>
  filter(var(democracy, na.rm = TRUE) > 0)
head(ross[,c("cty name", "year", "democracy", "infmort unicef")])
```

##	#	A tibble:	6 x 4		
##		cty_name	year	democracy	<pre>infmort_unicef</pre>
##		<chr></chr>	<dbl></dbl>	<dbl></dbl>	<dbl></dbl>
##	1	Albania	1990	Θ	36
##	2	Albania	1995	1	30
##	3	Argentina	1970	Θ	59
##	4	Argentina	1980	Θ	33
##	5	Argentina	1990	1	25
##	6	Argentina	1995	1	22

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- **Time series, cross-sectional (TSCS) data**: smaller *n*, large *T* (a political science term, mostly)



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- Assume that if we could measure c_i , we would have the correct CEF:

$$\mathbb{E}[u_{it} \mid \mathbf{X}_{it}, c_i] = 0 \implies \mathbb{E}[Y_{it} \mid \mathbf{X}_{it}, c_i] = \mathbf{X}'_{it}\boldsymbol{\beta} + c_i$$

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- Both problems arise out of ignoring the **unmeasured heterogeneity** inherent in *c*_{*i*}

```
##
## t test of coefficients:
##
## Estimate Std. Error t value Pr(>|t|)
## (Intercept) 10.3338 0.6279 16.46 < 2e-16 ***
## democracy -0.5639 0.1135 -4.97 1.3e-06 ***
## log(GDPcur) -0.2486 0.0287 -8.66 7.7e-16 ***
## ---
## Signif. codes:
## 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1</pre>
```

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- Pooled OLS will be inconsistent for the CEF parameters, $\pmb{\beta}$.

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- Two approaches that leverage repeated observations:
 - **Differencing** look at changes over time.
 - Fixed effects look at relationships within units.

2/ First Differencing Methods

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= $\Delta \mathbf{X}'_{i}\boldsymbol{\beta} + \Delta u_{i}$

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- Under these assumptions, pooled OLS on the differences is consistent.

3/ Fixed Effects Methods

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$$\begin{split} \overline{Y}_{i} &= \frac{1}{T} \sum_{t=1}^{T} \left[\mathbf{X}_{it}' \boldsymbol{\beta} + c_{i} + u_{it} \right] \\ &= \left(\frac{1}{T} \sum_{t=1}^{T} \mathbf{X}_{it}' \right) \boldsymbol{\beta} + \frac{1}{T} \sum_{t=1}^{T} c_{i} + \frac{1}{T} \sum_{t=1}^{T} u_{it} \\ &= \overline{\mathbf{X}}_{i}' \boldsymbol{\beta} + c_{i} + \overline{u}_{i} \end{split}$$

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- This regression is sometimes called the "between regression"

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- · Center every covariate and the outcome at its within-unit mean.
- c_i drops out because its within-unit mean is itself (time-constant).
- If we write $\ddot{Y}_{it} = Y_{it} \overline{Y}_{i}$, then we can write this more compactly as:

$$\ddot{Y}_{it} = \ddot{\mathbf{X}}_{it}' \boldsymbol{\beta} + \ddot{u}_{it}$$

Fixed effects with Ross data

```
library(fixest)
fe.mod <- fixest::feols(
    log(kidmort_unicef) ~ democracy + log(GDPcur) | id,
    data = ross, vcov = "hetero")
summary(fe.mod)</pre>
```

```
## OLS estimation, Dep. Var.: log(kidmort_unicef)
## Observations: 237
## Fixed-effects: id: 53
## Standard-errors: Heteroskedasticity-robust
## Estimate Std. Error t value Pr(>|t|)
## democracy -0.156 0.0314 -4.97 0.0000015379 ***
## log(GDPcur) -0.354 0.0252 -14.03 < 2.2e-16 ***
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
## RMSE: 0.18124 Adj. R2: 0.95396
## Within R2: 0.711842</pre>
```

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- u_{it} uncorrelated with all covariates for unit *i* at any point in time.
- Rules out lagged dependent variables, since $Y_{i,t-1}$ is a function of $u_{i,t-1}$.

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 - Any time-constant variable gets "absorbed" by the fixed effect.
- Can include interactions between time-constant and time-varying variables, but lower order term of the time-constant variables get absorbed by fixed effects too.

• Pooled model with a time-constant variable, proportion Islamic:

```
library(lmtest)
p.mod <- lm(log(kidmort_unicef) ~ democracy + log(GDPcur) + islam, data = ross)
coeftest(p.mod, vcov = vcovHC)</pre>
```

```
##
## t test of coefficients:
##
             Estimate Std. Error t value Pr(>|t|)
##
  (Intercept) 10.36014 0.58133 17.82 < 2e-16 ***
##
  democracy -0.47634 0.09441 -5.05 9.6e-07 ***
##
  log(GDPcur) -0.25597 0.02671 -9.58 < 2e-16 ***
##
## islam
         0.00855 0.00106 8.06 5.2e-14 ***
## ---
## Signif. codes:
## 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

Time-constant variables

• FE model, where the islam variable drops out, along with the intercept:

```
fe.mod2 <- feols(
    log(kidmort_unicef) ~ democracy + log(GDPcur) + islam | id,
    data = ross, vcov = "hetero")
summary(fe.mod2)</pre>
```

```
## OLS estimation, Dep. Var.: log(kidmort unicef)
## Observations: 220
## Fixed-effects: id: 45
## Standard-errors: Heteroskedasticity-robust
##
          Estimate Std. Error t value Pr(>|t|)
## democracy -0.144 0.0347 -4.14 0.000054978
## log(GDPcur) -0.360 0.0257 -14.00 < 2.2e-16
##
## democracy
             ***
## log(GDPcur) ***
## ... 1 variable was removed because of collinearity (islam)
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
## RMSE: 0.185449 Adj. R2: 0.949078
                 Within R2: 0.717818
##
```

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 - Pros: easy to implement and gives correct SEs.
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 - Usually better to use dedicated software like fixest package in R.

##		Estimate	Std. Error	t value	Pr(> t)
##	(Intercept)	11.385	0.6306	18.05	2.01e-42
##	democracy	-0.156	0.0366	-4.27	3.14e-05
##	log(GDPcur)	-0.354	0.0295	-11.99	8.65e-25
##	idARG	1.263	0.1425	8.87	6.82e-16
##	idARM	0.462	0.1287	3.59	4.20e-04
##	idBEN	1.334	0.0884	15.08	7.10e-34

coeftest(fe.mod)[1:2,]

##		Estimate	Std. Error	Ζ	value	Pr(> z)
##	democracy	-0.156	0.0314		-4.97	6.69e-07
##	log(GDPcur)	-0.354	0.0252		-14.03	1.08e-44

4/ Clustering

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- Called clustering or clustered dependence

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- Outcome varies at the unit-level, Y_{ig} and the main independent variable varies at the cluster level, X_g .

$$Y_{ig} = \beta_0 + X_g \beta_1 + v_{ig}$$
$$= \beta_0 + X_g \beta_1 + c_g + u_{ig}$$

• u_{ig} unit error component with $\mathbb{V}[u_{ig}|X_g] = \sigma_u^2$

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•
$$\rightsquigarrow \mathbb{V}[v_{ig}|X_g] = \sigma_c^2 + \sigma_u^2$$

• What if we ignore this structure and just use v_{ig} as the error?

• Covariance between two units *i* and *s* in the same cluster:

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Correlation between units in the same group is called the intra-class correlation coefficient, or ρ_c:

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• Zero covariance of two units *i* and *s* in different clusters *g* and *k*:

$$\operatorname{Cov}[v_{ig}, v_{sk}] = 0$$

•
$$\mathbf{v}' = \begin{bmatrix} v_{1,1} & v_{2,1} & v_{3,1} & v_{4,2} & v_{5,2} & v_{6,2} \end{bmatrix}$$

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$$\mathbb{V}[\mathbf{V}|\mathbf{X}] = \begin{bmatrix} \sigma_c^2 + \sigma_u^2 & \sigma_c^2 & \sigma_c^2 & 0 & 0 & 0 \\ \sigma_c^2 & \sigma_c^2 + \sigma_u^2 & \sigma_c^2 & 0 & 0 & 0 \\ \sigma_c^2 & \sigma_c^2 & \sigma_c^2 + \sigma_u^2 & 0 & 0 & 0 \\ 0 & 0 & 0 & \sigma_c^2 + \sigma_u^2 & \sigma_c^2 & \sigma_c^2 \\ 0 & 0 & 0 & \sigma_c^2 & \sigma_c^2 + \sigma_u^2 & \sigma_c^2 \\ 0 & 0 & 0 & \sigma_c^2 & \sigma_c^2 + \sigma_u^2 & \sigma_c^2 \end{bmatrix}$$

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• Variance matrix under i.i.d.:

$$\mathbb{V}[\mathbf{v}|\mathbf{X}] = \begin{bmatrix} \sigma_u^2 & 0 & 0 & 0 & 0 & 0 \\ 0 & \sigma_u^2 & 0 & 0 & 0 & 0 \\ 0 & 0 & \sigma_u^2 & 0 & 0 & 0 \\ 0 & 0 & 0 & \sigma_u^2 & 0 & 0 \\ 0 & 0 & 0 & 0 & \sigma_u^2 & 0 \\ 0 & 0 & 0 & 0 & 0 & \sigma_u^2 \end{bmatrix}$$

$$Y_{ig} = \beta_0 + X_g \beta_1 + c_g + u_{ig}$$

• $\mathbb{V}^0[\hat{eta}_1] =$ **conventional** OLS variance assuming i.i.d./homoskedasticity.

Effects of clustering

$$Y_{ig} = \beta_0 + X_g \beta_1 + c_g + u_{ig}$$

- + $\mathbb{V}^0[\hat{eta}_1] =$ conventional OLS variance assuming i.i.d./homoskedasticity.
- Let $\mathbb{V}[\hat{\beta}_1]$ be the true sampling variance under clustering.

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- Let $\mathbb{V}[\hat{\beta}_1]$ be the true sampling variance under clustering.
- When clusters are balanced, $n^* = n_g$, comparison of clustered to conventional:

 $\mathbb{V}[\hat{\beta}_1] \approx \mathbb{V}^0[\hat{\beta}_1] \left(1 + (\mathbf{n}^* - 1) \boldsymbol{\rho}_c\right)$

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$$\mathbb{V}[\hat{\beta}_1] \approx \mathbb{V}^0[\hat{\beta}_1] \left(1 + (n^* - 1)\rho_c\right)$$

- True variance will be higher than conventional when within-cluster correlation is positive, $\rho_c > 0$.

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• Assumptions:

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- We can write the OLS estimator as:

$$\hat{\boldsymbol{\beta}} = \left(\sum_{g=1}^{m} \mathbb{X}_{g}' \mathbb{X}_{g}\right) \left(\sum_{g=1}^{m} \mathbb{X}_{g}' \mathbf{Y}_{g}\right)$$
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- With small-sample adjustment (reported by most software):

$$\widehat{\mathbf{V}}_{\widehat{\boldsymbol{\beta}}}^{\mathrm{CLI}} = \frac{m}{m-1} \frac{n-1}{n-k} \left(\mathbb{X}' \mathbb{X} \right)^{-1} \left(\sum_{g=1}^m \mathbb{X}'_g \widehat{\mathbf{v}}_g \widehat{\mathbf{v}}_g' \mathbb{X}_g \right) \left(\mathbb{X}' \mathbb{X} \right)^{-1}$$

Example: Gerber, Green, Larimer

Dear Registered Voter:

WHAT IF YOUR NEIGHBORS KNEW WHETHER YOU VOTED?

Why do so many people fail to vote? We've been talking about the problem for years, but it only seems to get worse. This year, we're taking a new approach. We're sending this mailing to you and your neighbors to publicize who does and does not vote.

The chart shows the names of some of your neighbors, showing which have voted in the past. After the August 8 election, we intend to mail an updated chart. You and your neighbors will all know who voted and who did not.

DO YOUR CIVIC DUTY - VOTE!

MAPLE DR	Aug 04	Nov 04	Aug 06
9995 JOSEPH JAMES SMITH	Voted	Voted	
9995 JENNIFER KAY SMITH		Voted	
9997 RICHARD B JACKSON		Voted	
9999 KATHY MARIE JACKSON		Voted	

Social pressure model

```
load("../assets/gerber_green_larimer.RData")
library(lmtest)
social$voted <- 1 * (social$voted == "Yes")
social$treatment <- factor(
   social$treatment,
   levels = c("Control", "Hawthorne", "Civic Duty", "Neighbors", "Self")
)
mod1 <- lm(voted ~ treatment, data = social)
coeftest(mod1)</pre>
```

##				
##	t test of coefficien	nts:		
##				
##		Estimate	Std. Error	t value
##	(Intercept)	0.29664	0.00106	279.53
##	treatmentHawthorne	0.02574	0.00260	9.90
##	<pre>treatmentCivic Duty</pre>	0.01790	0.00260	6.88
##	treatmentNeighbors	0.08131	0.00260	31.26
##	treatmentSelf	0.04851	0.00260	18.66
##		Pr(> t)		
##	(Intercept)	< 2e-16	* * *	
##	treatmentHawthorne	< 2e-16	* * *	
##	<pre>treatmentCivic Duty</pre>	5.8e-12	***	
##	treatmentNeighbors	< 2e-16	***	
##	treatmentSelf	< 2e-16	* * *	
##				

Social pressure model, CRSEs

library(sandwich)

coeftest(mod1, vcov = sandwich::vcovCL(mod1, cluster = social\$hh_id))

##				
##	t test of coefficier	nts:		
##				
##		Estimate	Std. Error t value	
##	(Intercept)	0.29664	0.00131 226.52	
##	treatmentHawthorne	0.02574	0.00326 7.90	
##	<pre>treatmentCivic Duty</pre>	0.01790	0.00324 5.53	
##	treatmentNeighbors	0.08131	0.00337 24.13	
##	treatmentSelf	0.04851	0.00330 14.70	
##		Pr(> t)		
##	(Intercept)	< 2e-16	***	
##	treatmentHawthorne	2.8e-15	***	
##	<pre>treatmentCivic Duty</pre>	3.2e-08	***	
##	treatmentNeighbors	< 2e-16	***	
##	treatmentSelf	< 2e-16	***	
##				
##	Signif. codes:			
##	0 '***' 0.001 '**' 0).01 '*' (0.05 '.' 0.1 ' ' 1	

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 - CRSEs can be incorrect with a small (< 50 maybe) number of clusters